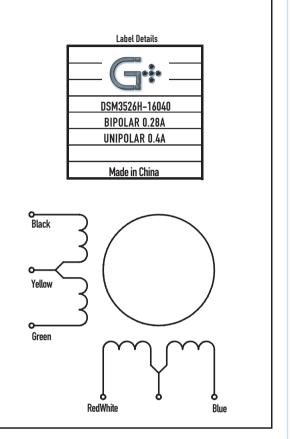
[Mechanical Drawings for DSMH series]

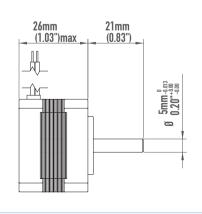
DSM3526H-16040

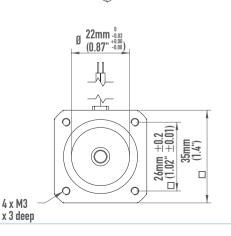
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	0. 4 1		1					
Step Angle			1.8°					
Step Angle Accuracy			±5					
Holding Torque (Bipolar)			55n	nNm	7.5oz-in			
Current (RMS)			Bip	olar	Unipolar			
			0.9A		0.65A			
Winding Resistance (Ω)			15					
Wind	Winding Inductance (mH)			7.5				
Detent Torque			10mNm 1.4oz-in			z-in		
Rotor Inertia (gcm²)			10					
	Insulation Class			Class B, 100M Ω				
Mass			150					
Bearings			Ball Bearings 695ZZ					
Direction of			Yellov	v +VE	White +VE			
Rota	ation	Step	Black	Green	Red	Blue		
	CCW	1	ON	OFF	ON	OFF		
lī		2	ON	OFF	OFF	OFF		
		3	ON	OFF	OFF	ON		
		4	OFF	OFF	OFF	ON		
C _K		5	OFF	ON	OFF	ON		
		6	OFF	ON	OFF	OFF		
†		7	OFF	ON	ON	OFF		
		8	OFF	OFF	ON	OFF		
Sequence shown is for half-step excitation. For full step excitation energise as steps 1,3,5,7								









[Mechanical Drawings for DSMH series]

DSM3526H-14080

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	Otan Amala			1	00				
Step Angle		1.8°							
Step Angle Accuracy		±5							
Holding Torque		55mNm 7.5oz		z-ın	Label Details				
Current (RMS)		Bipolar 830mA							
Winding Resistance (Ω)		630IIIA 4							
Winding Inductance (mH)		2.3				DSM3526H-14080			
Detent Torque		10mNm 1.4oz-in		z-in	BIPOLAR 830mA				
Rotor Inertia (gcm²)		10							
Insulation		Class B, 100M Ω							
Mass		150g				Made in China			
Bearings		Ball Bearings 695ZZ (China)							
Direction of Step		R e d	Black	Yellow	White	Red			
→ M33		1	+	-	+	-	3 /		
	↓	2	+	-	OFF	OFF			
		3	+	-	-	+	 		
	4	OFF	OFF	-	+				
S)	23	5	-	+	_	+	Black		
lacksquare	6	-	+	OFF	OFF	\sim			
		7	-	+	+	-			
[V	8	OFF	OFF	+	-			
	Sequence shown is for half–step excitation. For full step excitation energise as steps 1,3,5,7						Yellow White		

